MARKANT

Matrix Click Manual

Control Unit



5 Operation / 5.1 Performing a Position Reset Procedure



Risk of minor or moderate injury through crushing

Collision Detection (ISP) is inactive during start-up and reset processes. This may lead to minor or moderate injury through crushing.

Ensure that no persons or objects are in the table's range of motion.

Notice

When in use for the first time, wait 10 seconds a.er plugging in the Power cord to reset the table. The green LED lights up quickly to show the table can be resetted.

Before using the Matrix Click System a Postion Reset Procedure must be carried out.

You do this as follows:

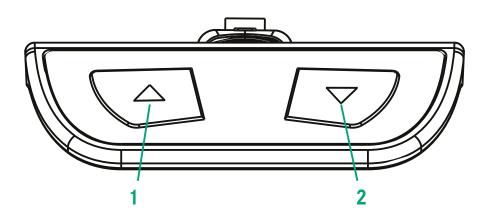
- > Press and hold the DOWN Key until the table stops at the lower position limit
- Release the DOWN Key
- Press and hold the DOWN Key again The table will move down slightly, then up again
- Release the DOWN Key

The Position Reset Procedure is complete

Notice

If your Matrix Click system has been parameterized with additional stopping points (e.g. a Safety Area or Container Stop Position), repeat Step 3 until the table has moved upwards again.

5.2 Basic functions



- 1 UP button
- 2 DOWN button
- 3 Memory Position Keys
- 4 SAVE Key
- 5 Display

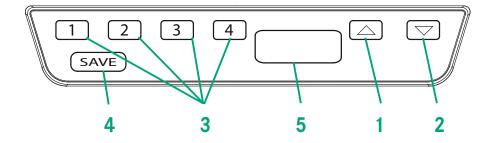


Table top up

- Press the UP button on the hand switch.
- > Keep the button pressed until the desired table top height is reached.

Table top down

- > Press the DOWN button on the hand switch.
- Keep the button pressed until the desired table top height is reached.

Notice

The table top moves up or down until you release the button or until the maximum or minimum height of the table top is reached.

Notice

The hand switch shouldn't be assembled underneath or in direct proximity to metal parts.

Notice

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The hand switch was tested for interference immunity against high frequent electromagnetic fields according to EC default standard EN 61000-6-2:2005. To ensure an interference-free operation all electrical appliances in the surrounding area must comply with the test standard EN55014.



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5.3 Extended functions

Container-Stop on

Move the table to the desired position.

and off

Then press **UP/DOWN** button simultaneously for 10 sec.

(only possible in lower half of stroke)

Container-Stop is now active.

Shelf stop on and off (only possible in

upper half of stroke)

Move the table to the desired position.

Then press **UP/DOWN** button simultaneously for 10 sec.

Shelf-Stop is now active.

5.4.1 Saving a memory position

Move the table to the desired height

The display shows the Table Top height

Press the SAVE Key

Press the Memory Position Key 2, 5 2, 7 3

The display shows S 2 Afer about two seconds, the Table Top height is displayed again

5.4.2 Adjusting the table to a memory position

> Press and hold the required Memory Position Key (e.g. 2) 2, 2

The Table Top will move until the saved Table Top height has been reached

If you release the Key before the Memory Position is reached, the table will stop

Release the Memory Position Key

Release the Memory Position Key

5.4.3 Changing the height display (cm/inch)

DMUI-HSU Handsets can display the height of the Table Top in both centimeters and inches. To change the displayed unit of measurement:

Press and hold Memory Position Keys 1 and 2, alongside the UP Key

The display shows S and a number, e.g. S 7

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- Press the UP Key or DOWN Key until the display shows S 5 , 5 The display shows S 5
- ➤ Press the SAVE Key

If the display was previously set to cm, it is now set to inches If the display was previously set to inches, it is now set to cm

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5.5 System Information

| Signal | Message | Required Actions |
|------------------------------------|---|--|
| No Light | System operating normally System not connected | Operate the Matrix Click System as normal. See configuration on page 13, picture 9. |
| Red Light Blinking | System Error Warning | Release all keys and wait for 5 seconds. Then, try to repeat the action again. Disconnect all components from the PowerHub. Disconnect the Power Hub from the Mains. Check the Power Hub for overheating. Let cool if necessary. Check all connections and reconnect the system. If problem persists: Perform a Position Reset Procedure (Chapter 5.1). Contact Markant. |
| Green Light Blinking | System Start-up Reset in Progress Duty Cycle Exceeded | Wait until the LED has stopped blinking to continue. Do not press any buttons. Remove the obstruction from the Table System. Remove unnecessary loads from the Table Top Operate the Matrix Click System as normal. |
| Green Light flashing Rapidly | Position Reset Required. | Performing a Position Reset Procedure. |

Notice Do not operate the Matrix Click system if problems persist. Contact Markant for further information.

5.6 Troubleshooting

| Problem | Possible cause | Solution | | |
|-------------------------------------|--|--|--|--|
| The table does not move | The system is not plugged in. | insure that the system has been connected to the Power lub correctly. | | |
| move | The Actuator is not connected properly. | Ensure that the Actuator is properly connected to all components of the system. | | |
| | Poor plug connection. | Ensure that all plugs have been connected properly. | | |
| | The Actuator is defective. | Contact Markant. | | |
| | The hand switch is defective. | Contact Markant. | | |
| The table only moves slowly down- | There was power failure while the table was in motion. | Perform a Position Reset Procedure (see Chapter 5.1 Performing a Position Reset Procedure) . | | |
| wards | The Power Hub was disconnected while the device was in motion. | | | |
| | Reset required. | | | |
| | The Actuator is defective. | Contact Markant. | | |
| The hand switch does not work | The hand switch is defective. | Contact Markant. | | |

6 Factory reset

To reset the Matrix Click System to its Factory Settings with a Basic Handset:

- > Press the UP and DOWN button simultaneously, then release
- Press and hold the UP and DOWN button for 10 sec The LED will light up in Red
- > When the LED light begins to blink, release the UP and DOWN button
- > The Matrix Click system has now been reset to its factory settings

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7 Service functions / 7.1 Safety



Crushing and shearing hazard!

When restoring the control system to the factory settings and when resetting, the collision protection ISP [Intelligent System Protection] is inactive.

 Make sure that no objects or persons are in the danger zone (safety distance > 25 mm) and that they do not reach into the danger zone

8 Cleaning



Property damage due to improper cleaning.

- Do not use solvents or abrasives
- > Use only dry, so. cloths for cleaning
- Always keep the handset and plug connectors free of dust deposits!
- > Clean the control system and handset with a dry, soft cloth

9 Disposal

Environmental damage due to improper disposal.

Notice

 Proper disposal serves as environmental protection and prevents possible harmful effects to humans and the environment

Information on the disposal of electrical and electronic equipment in the European Union:



Within the European Union, the disposal of electrically operated equipment is governed by national regulations based on the EU Directive 2012/19/EU on Waste Electrical and Electronic Equipment (WEEE). In accordance with this, the device must no longer be disposed of with municipal waste or household waste. The device is accepted free of charge at municipal collection points or recycling centers. Product packing consists largely of recyclable materials. Dispose of it in an environmentally friendly manner and bring it in for recycling.



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10 Fehlder Codes DM-System

| Nr. | Туре | DMUI-TOUCH-B | DMUI- TOUCH-C | Name | Trigger | FW Reaction | Required Actions (to satisfy FW) |
|-----|-------|-----------------------|------------------|--|--|--|--|
| 0 | Еггог | RED_BLINK_SLOW_CONT | | Invalid | Never (would be a bug) | | |
| 1 | Error | RED_BLINK_SLOW_CONT | "Егг"/No | FW Assert | Firmware runs into critical situation, operation cannot continue (might be combined with No. 21) | Hard Stop | Power Cycle |
| 2 | Error | RED_BLINK_SLOW_CONT | "Err"/No | Motor Over Current | (RESERVED – NOT YET IMPLEMENTED) Motor current overshoot maximal (parameterized) current. | Hard Stop | Release Button, try again |
| 3 | Error | RED_BLINK_SLOW_CONT | "Егг"/No | DC Over Voltage | DC voltage exceeds limit | Deceleration | Release Button, try again |
| 4 | Error | RED_BLINK_SLOW_CONT | "Err"/"Con" | LIN Communication | Communication timeouts, Checksum/communication errors, short circuit on the communication bus | Hard Stop | Release Button, try again Power Cycle |
| 5 | Busy | GREEN_BLINK_SLOW_CONT | "ISP" | ISP (Collision) | Strain gauge sensor or motor current evaluation signaled a collision event | Hard Stop + Drive Back | Release Button, try again |
| 7 | Busy | GREEN_BLINK_SLOW_CONT | "hot" | Power Supply Overtemperature | Power supply voltage deceeds parameterized limit (self-protection feature of DMPx) | Active movement can be finished, new driving cycle blocked | Cool down power supply (voltage has to be above overtemperature limit), try again |
| 8 | Busy | RED_BLINK_SLOW_CONT | "Егг"/No | Impulse Detection Timeout | No position feedback (impulses) within a configured time. | Hard Stop | Reference movement |
| 9 | Busy | GREEN_BLINK_SLOW_CONT | "hot" | Driving Duty Cycle | Operating time (movement) exceeds parameterized limit | Active movement can be finished, new driving cycle blocked | Wait parameterized time, try again |
| 10 | Busy | GREEN_BLINK_SLOW_CONT | "hot" | MCD Overtemperature | MCD temperature sensor or μC temperature sensor overshoots parameterized temperature limits | Deceleration, new driving cycle blocked | Cool down electronic, try again |
| 11 | Error | RED_BLINK_SLOW_CONT | "Err"/No | Cannot Follow (Movement) | Desired speed/acceleration cannot be achieved. | Hard Stop | Release Button, try again |
| 12 | Error | RED_BLINK_SLOW_CONT | "Err"/No | Power Stage Overcurrent | MOSFET current(s) exceed congured limits. | Hard Stop | Release Button, try again |
| 13 | Error | RED_BLINK_SLOW_CONT | "Егг"/No | DC Under Voltage | DC voltage deceeds minimal required operating voltage for the microcontroller | Hard Stop (Fault cannot be stored in memory) | Release Button, try again |
| 14 | Error | RED_BLINK_SLOW_CONT | "Err"/No | Out Of Sync | Position of actuators is out of sync | Hard Stop | Release Button, try again |
| 15 | Error | RED_BLINK_SLOW_CONT | "Err"/No | Strain Gauge | Strain gauge signal saturates: broken sensor or wires | Deceleration, Not starting | Release Button, try again |
| 17 | Error | RED_BLINK_SLOW_CONT | "Err"/No | Compound Error | Something went wrong during wedding sequence, bus communication errors, faulty actuators, network configuration not consistent, network not working | Cannot happen during movement | Power Cycle and/or S0 |
| 18 | Error | RED_BLINK_SLOW_CONT | "Егг"/No | Nodes Incompatible (Wedding Sequence) | Parameterization and/or fimware version of drives within a compound are not compatible | Cannot happen during movement | Compatible parameterization and/or firmware and/or S0 |
| 19 | Еггог | RED_BLINK_SLOW_CONT | "Err"/No | Wrong Number of Drives | Desired number of drives (according parameter) does not match with number of drives within the setup | Cannot happen during movement | Number of drives in the setup has to match with desired/parameterized number of drives options |
| 20 | Еггог | RED_BLINK_SLOW_CONT | "Err"/No | Motor short circuit and/or open load | Short circuit and/or open load detection of the microcontroller-internal detection mechanism triggered (short circuit or open load on at least one of the 3 phases of the motor) | Movement cannot be initiated | No short circuit nor open load on the three phases of the motor |
| 21 | Error | RED_BLINK_SLOW_CONT | "Err"/No | Critical firmware condition (safe-state) | A critical condition prevents correct firmware execution (watchdog, task runtime error) | Hard Stop | Power Cycle |
| 22 | Error | RED_BLINK_SLOW_CONT | "Егг"/No | Powersupply overload | Power supply overload was detected (DMSystem voltage drop mechanism) | Hard Stop | Release Button, try again |
| 23 | Еггог | RED_BLINK_SLOW_CONT | "Err"/No | Motor Under Voltage | Supply voltage level is too low (according parameter) for driving the motor. | Hard Stop (or movement won't start) | Supply voltage has to be above limit, release button, try again |